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## Improved estimation of the mean in one-parameter exponential families with known coefficient of variation

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**Abstract:** The value for which the mean square error of a biased estimator  $aT$  for the mean  $\mu$  is less than the variance of an unbiased estimator  $T$  is derived by minimizing  $MSE(aT)$ . The resulting optimal value is  $1/[1+c(n)v^2]$ , where  $v = \sigma/\mu$ , is the coefficient of variation. When  $T$  is the UMVUE  $X$ , then  $c(n) = 1/n$ , and the optimal value becomes  $1/(n+v^2)$  (Searls, 1964). Whenever prior information about the size of  $v$  is available the shrinkage procedure is useful. In fact for some members of the one-parameter exponential families it is known that the variance is at most a quadratic function of the mean. If we identify the pertinent coefficients in the quadratic function, it becomes easy to determine  $v$ .

## Introduction

It is known that one important way of improving estimation of distribution parameters is by way of employing biased estimation procedures. The mean square is the most popular and widely used criterion to show when a biased estimator is better than an unbiased estimator. In other words the region of improvement of estimation is obtained from comparing the scalar or (matrix) mean square error (MSE) of the biased estimator with the variance

(covariance matrix) of the unbiased estimator. In this connection Perlman (1972) provides necessary and sufficient condition for the existence of a real  $a \in (0, 1)$  such that a shrinkage of an unbiased vector-valued estimator would result in an improvement in MSE. Bibby (1972) and Bibby and Toutenburg (1977, 1978) discuss biased estimation procedures and estimators that result from unbiased procedures and estimators. Kleffe (1985) uses a general result due to Perlman to derive uniformly better estimators. Further results which relate to the improvement of the estimator of the population mean are given in Searls (1964), Khan (1968), Gleser and Healy (1976), Arnholt and Hebert (1995). In the current paper we concentrate on certain members of the one-parameter exponential families. Under the assumption that the coefficient of variation is known *a priori* we derive estimators for the mean with minimum MSE.

## A Review of some Results

Suppose that a univariate variable  $X \sim \mathcal{D}(\mu, \sigma^2)$ ,  $\mu \neq 0$ , where  $\mathcal{D}$  is any distribution, and that the coefficient of variation  $v = \sigma/|\mu|$  or the noise-to-signal,  $\sigma/|\mu|$ ,  $\mu < 0$ , is known. As a consequence the variance of  $X$  can be written as  $\sigma^2 = v^2\mu^2$ . It is not uncommon that experience and results obtained from applications justify the assumption of known  $v$ . The prior information about  $v$  can be incorporated in distribution models. For example, in the case of the exponential distribution  $v = 1$ . The statistical literature provides some results that relate to this topic.

Suppose that an iid sample  $\mathbf{X} = (X_1, \dots, X_n)'$  is available. Based on the assumption that  $v$  is known Searls (1964) shows that an improvement of es-

timination of the mean is possible

$$C(a)$$

According to Khan (1968), in

$$C(a, 1-a) = \{T(\mathbf{X}) | T(\mathbf{X})\}$$

(see Examples below) the weight of  $T_1(\mathbf{X})$  or  $T_2(\mathbf{X})$  in MSE when the distribution is known. Gleser to a wider class

$$C(a_1, a_2) = \{T(\mathbf{X}) | T(\mathbf{X})\}$$

(see Examples below) that of  $T_1(\mathbf{X})$  and  $T_2(\mathbf{X})$  of the mean that has minimum MSE. The further enrichment to the above estimators. This paper studies intervals on which one-parameter exponential f

### Example 1 [Searls (1964)]

Suppose  $\mathbf{X} = (X_1, \dots, X_n)$  mean  $\mu$ ,  $\mu \neq 0$ , and variance  $a \sum_{i=1}^n X_i$ ,  $a \in (0, 1)$ , as an estimator the purpose here is a real number. The optimal  $a$  is

estimation of the mean is possible by considering a class of shrunken estimators

$$C(a) = \{aT(\mathbf{X}) | a \in (0, 1)\}.$$

According to Khan (1968), in the class

$$C(a, 1-a) = \{T(\mathbf{X}) | T(\mathbf{X}) = aT_1(\mathbf{X}) + (1-a)T_2(\mathbf{X}), a \in [0, 1]\}$$

(see Examples below) the weighted unbiased estimator  $T(\mathbf{X})$  dominates each

of  $T_1(\mathbf{X})$  or  $T_2(\mathbf{X})$  in MSE when the coefficient of variation for the normal distribution is known. Gleser and Healy (1976) extend the results of Khan

to a wider class

$$C(a_1, a_2) = \{T(\mathbf{X}) | T(\mathbf{X}) = a_1T_1(\mathbf{X}) + a_2T_2(\mathbf{X}), a_1, a_2 \in (0, 1)\}$$

(see Examples below) that consists of both biased and unbiased estimators ( $T_1(\mathbf{X})$  and  $T_2(\mathbf{X})$ ) of the mean. They derive a biased estimator of the mean that has minimum MSE. The work by Arnholt and Hebert (1995) is a further enrichment to the above estimation procedure for a general class of estimators. This paper studies improvement of estimation of the mean and discusses intervals on which improvement in estimation is attained for the one-parameter exponential families of distributions.

### Example 1 [Searls (1964)]

Suppose  $\mathbf{X} = (X_1, \dots, X_n)'$  is a random sample from a distribution with mean  $\mu$ ,  $\mu \neq 0$ , and variance  $\sigma^2$ . We can consider the statistic  $T(\mathbf{X}) = a \sum_{i=1}^n X_i$ ,  $a \in (0, 1)$ , as an estimator for  $\mu$ . The best choice of a constant for the purpose here is a real number  $a \in (0, 1)$  which minimizes  $MSE[aT(\mathbf{X})]$ . The optimal  $a$  is

$$a^* = \frac{n + \sigma^2}{1}$$

that an improvement of es-

is available. Based on the

1. The statistical literature

distribution models. For example,

tion of known  $v$ . The prior

that experience and results

ence the variance of  $\mathbf{X}$  can

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$(\sigma^2)$ ,  $\mu \neq 0$ , where  $\mathcal{D}$  is any

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option that the coefficient of

certain members of the one-

(1976), Arnholt and Hebert

e population mean are given

ators. Further results which

(1985) uses a general result

s and estimators that result

and Bibby and Tourenburg

ector-valued estimator would

on for the existence of a real

In this connection Perlman

Hence, the estimator of the mean  $\mu$  with minimum MSE is  $T^*(\mathbf{X}) = a^*T(\mathbf{X})$ .

### Example 2 [Khan (1968)]

Suppose  $\mathbf{X} = (X_1, \dots, X_n)'$  is an iid random sample from  $\mathcal{N}(\mu, v^2\mu^2)$ ,  $\mu \neq 0$ , and the coefficient of variation  $v$  is known. Khan considers two unbiased estimators for  $\mu$ , namely the sample mean  $T_1(\mathbf{X}) = \bar{X}$  and a linear function of the square root of the total sum of squares  $S_n$

$$T_2(\mathbf{X}) = c_n \left[ \sum_{i=1}^n (X_i - \bar{X})^2 \right]^{1/2} = c_n S_n,$$

where the constant

$$c_n = n^{1/2} (2v)^{-1/2} \frac{\Gamma((n-1)/2)}{\Gamma(n/2)}.$$

The variances of the two estimators are

$$\text{Var}T_1(\mathbf{X}) = n^{-1}v^2\mu^2$$

and

$$\text{Var}T_2(\mathbf{X}) = \mu^2 \left[ -1 + \frac{n-1}{2} \times \frac{\Gamma^2((n-1)/2)}{\Gamma^2(n/2)} \right].$$

The weighted sum of the unbiased estimators  $T_1(\mathbf{X})$  and  $T_2(\mathbf{X})$  belongs to the class  $\mathcal{C}(a, 1-a)$  given above with  $\text{Var}T(\mathbf{X}) = a^2\text{Var}T_2(\mathbf{X}) + (1-a)^2\text{Var}T_1(\mathbf{X})$

This last result is given purely as the sum of two variances because the two estimators  $T_1(\mathbf{X})$  and  $T_2(\mathbf{X})$  are uncorrelated. In fact, by normality, they are independent.

That value of  $a$  which minimizes  $\text{Var}T(\mathbf{X})$  is

$$\begin{aligned} a^* &= \frac{\text{Var}T_1(\mathbf{X})}{\text{Var}T_1(\mathbf{X}) + \text{Var}T_2(\mathbf{X})} \\ &= v \left\{ \left( v + n \left[ -1 + \frac{n-1}{2} \times \frac{\Gamma^2((n-1)/2)}{\Gamma^2(n/2)} \right] \right) \right\}^{-1}. \end{aligned}$$

The resulting unbiased estimator is each one of  $T_1(\mathbf{X})$  and  $T_2(\mathbf{X})$ , any other unbiased estimator

### Example 3 [Gleser and H

An extension of the result they consider a wider class necessarily a weighted linear

$$\mathcal{C}(a_1, a_2) = \{T(\mathbf{X}) | T(\mathbf{X}) = a_1 T_1(\mathbf{X}) + a_2 T_2(\mathbf{X})\}$$

where  $T_1(\mathbf{X})$  and  $T_2(\mathbf{X})$  are

They show that a shrinkage

$$s(v, n) = (d_n)^{-1}$$

where  $d_n = -1 + v(n-1)c_n$

with uniformly minimum M

### Example 4 [Arnholt and

Suppose  $\mathbf{X} = (X_1, \dots, X_n)'$  and that the coefficient of median. Note that in this case where  $\kappa_n$  is the variance of the optimal biased estimator of  $M_n$  given by

$T_n$

The resulting unbiased estimator  $T_3(\mathbf{X}) = a^*T(\mathbf{X})$  is uniformly better than each one of  $T_1(\mathbf{X})$  and  $T_2(\mathbf{X})$ , and more generally it is uniformly better than any other unbiased estimator in the class  $C(a)$ .

**Example 3 [Gleser and Healy (1976)]**

An extension of the result by Khan is given by Gleser and Healy where they consider a wider class (a linear combination of  $T_1(\mathbf{X})$  and  $T_2(\mathbf{X})$ ), not necessarily a weighted linear combination)

$$C(a_1, a_2) = \{T(\mathbf{X}) | T(\mathbf{X}) = a_1T_1(\mathbf{X}) + a_2T_2(\mathbf{X}), a_1, a_2 \in [0, 1]\},$$

where  $T_1(\mathbf{X})$  and  $T_2(\mathbf{X})$  are as given in Khan.

They show that a shrinkage of the unbiased estimator  $T_3(\mathbf{X})$  multiplied by

$$s(a, n) = (d_n + vn^{-1}) / (d_n + vn^{-1} + vd_n n^{-1}),$$

where  $d_n = -1 + v(n - 1)c_n^{-2}n^{-1}$ , gives rise to a biased estimator

$$T_4(\mathbf{X}) = s(a, n)T_3(\mathbf{X})$$

with uniformly minimum MSE showing that  $T_4(\mathbf{X})$  dominates  $T_3(\mathbf{X})$ .

**Example 4 [Arnholt and Hebert (1995)]**

Suppose  $\mathbf{X} = (X_1, \dots, X_n)'$  is an iid random sample from  $N(\mu, v^2\mu^2)$ ,  $\mu \neq 0$ , and that the coefficient of variation  $v$  is known. Let  $M_n$  be the sample median. Note that in this case we have  $E(M_n) = \mu$  and  $Var(M_n) = \kappa_n v^2 \mu^2$ , where  $\kappa_n$  is the variance of the median of  $n$  iid standard normal variates. The optimal biased estimator of the mean  $\mu$  is a shrinkage of the sample median

$$T_{\kappa_n}(\mathbf{X}) = (\kappa_n v^2 + 1)^{-1} M_n$$

$M_n$  given by

in MSE is  $T^*(\mathbf{X}) = a^*T(\mathbf{X})$ .

han considers two unbiased

$\bar{X}$  and a linear function

$$= c_n S_n,$$

$$\frac{1}{(n-1)/2}$$

$$\frac{[T_2(n/2)]}{(n-1)/2}$$

$T_2(\mathbf{X})$  and  $T_3(\mathbf{X})$  belongs to the

variances because the two

in fact, by normality, they

$$\frac{1}{(n-1)/2}$$

$$\frac{1}{(n-1)/2}$$

with

$$MSE(T_{\kappa_n}(\mathbf{X})) = (\kappa_n v^2 \mu^2 + 1)(\kappa_n v^2 + 1)^{-1}$$

Comparison of the  $MSE(M_n)$  and  $MSE(T_{\kappa_n}(\mathbf{X}))$  shows that  $T_{\kappa_n}(\mathbf{X})$  is the more efficient of the two estimators.

## Improved Estimation and Intervals

### A Generalization of the Result by Searls

Suppose  $\mathbf{X} = (X_1, \dots, X_n)'$  is an iid sample from  $\mathcal{D}(\mu, \sigma^2)$ ,  $\mu \neq 0$ , and that on the basis of the sample there exists an unbiased estimator, say  $T(\mathbf{X})$ , for  $\mu$ . Let the variance of  $T(\mathbf{X})$  be  $Var[T(\mathbf{X})] = c(n)\sigma^2$ , where  $c(n)$  is a function of the sample size  $n$ . If we consider biased estimators of  $\mu$  from the class  $\mathcal{C}(a) = \{aT(\mathbf{X}) | a \in (0, 1)\}$ , we have  $E[aT(\mathbf{X})] = a\mu$ ,  $Var[aT(\mathbf{X})] = c(n)a^2\sigma^2$ , and hence  $MSE[aT(\mathbf{X})] = c(n)a^2\sigma^2 + (a - 1)^2\mu^2$ . Since  $(d/da)[MSE(a\bar{X})] = 2c(n)a\sigma^2 + 2(a - 1)\mu^2$  and  $(d^2/da^2)[MSE(aT(\mathbf{X}))] = 2c(n)\sigma^2 + 2\mu^2 > 0$ , it follows that the biased estimator with minimum MSE in the class  $\mathcal{C}(a)$  is

$$T^{**}(\mathbf{X}) = a^{**}T(\mathbf{X}), \quad a^{**} = \frac{1}{c(n)v^2 + 1}$$

Hence  $MSE[T^{**}(\mathbf{X})] = c(n)\sigma^2(c(n)v^2 + 1)^{-1} < c(n)\sigma^2$ , from which it is evident that the relative efficiency of  $T^{**}(\mathbf{X})$  in relation to  $T(\mathbf{X})$ , defined as  $Var[T(\mathbf{X})]/MSE[T^{**}(\mathbf{X})]$ , is  $c(n)v^2 + 1$ . Since  $c(n)v^2 + 1 > 1$  the estimator  $T^{**}(\mathbf{X})$  dominates the unbiased  $T(\mathbf{X})$ .

Note that the result by Searls is a special case of the above with  $c(n) = 1/n$ .

## The Improvement Interval

An issue closely associated with the concept of regions of improvement; domination in terms of the improvement interval while considering this point leads to the improvement interval lead to

As a consequence of the generalization which improvement is gained

$$I(c(n), v) = \{a \in (0, 1) | MSE[aT(\mathbf{X})] < MSE[T(\mathbf{X})]\}$$

We observe that when  $v$  is very large, the interval tends to diminish, and therefore the interval will not be of great interest. However, then all values of  $v$  between  $v_1$  and  $v_2$  mean.

In the following section we discuss some pertinent matters about on

## One-Parameter Exponential Family

The family of distribution functions of a one-parameter exponential family on  $\Theta$ , real-valued functions  $p(x, \theta)$  of  $F_\theta$  may

$$p(x, \theta) = h(x)g(\theta)$$

### The Improvement Interval

An issue closely associated with improved estimation is the determination of regions of improvement; in the univariate case these are intervals. Since domination in terms of the scalar MSE is limited to an interval it is worthwhile considering this point as well because all shrinkage factors from the improvement interval lead to admissibility of the more efficient estimator.

As a consequence of the generalized result above we can give the interval on which improvement is gained by

$$I(c(n), v) = \{a \in \mathbb{R}_+ \mid \frac{1 - c(n)v^2}{1 + c(n)v^2} > a > 1, v \in (0, 1)\}.$$

We observe that when  $v$  is very close to zero the improvement interval seems to diminish, and therefore the possibility of improved estimation by shrinkage will not be of great interest. On the other hand if  $v$  is not very close to zero, then all values of  $v$  between zero and one lead to improved estimation of the mean.

In the following section we introduce definitions and terminology and discuss pertinent matters about one-parameter exponential families of distributions.

### One-Parameter Exponential Families of Distributions

The family of distributions of a model  $\{P_\theta \mid \theta \in \Theta\}$ , is said to be a one-parameter exponential family, if there exist real-valued functions  $\eta(\theta)$ ,  $B(\theta)$  on  $\Theta$ , real-valued functions  $T$  and  $h$  on  $\mathbb{R}^p$ , such that the density (frequency) functions  $p(x, \theta)$  of  $P_\theta$  may be written

$$p(x, \theta) = h(x) \exp[\eta(\theta)T(x) - B(\theta)], x \in X \subset \mathbb{R}^p.$$

(1) shows that  $T_{\mu, \sigma^2}(\mathbf{X})$  is the

$$c(n)v^2 + 1)^{-1}$$

$D(\mu, \sigma^2)$ ,  $\mu \neq 0$ , and that

estimator, say  $T(\mathbf{X})$ , for  $\mu$ .

where  $c(n)$  is a function of

of  $\mu$  from the class  $C(a) =$

$E[aT(\mathbf{X})] = c(n)a^2\sigma^2$ , and

since  $(d/da)[MSE(a\hat{X})] =$

$2c(n)\sigma^2 + 2\mu^2 > 0$ , it

MSE in the class  $C(a)$  is

$$\frac{1}{c(n)v^2 + 1}$$

$c(n)\sigma^2$ , from which it is

relation to  $T(\mathbf{X})$ , defined as

$c(n)v^2 + 1 > 1$  the estimator

the above with  $c(n) = 1/n$ .

Note that the functions  $\eta$ ,  $B$  and  $T$  are not unique (Bickel and Doksum, 2000, p. 49).

The families of distributions obtained from one-parameter exponential families are also themselves one-parameter exponential families. Suppose  $\mathbf{X} = (X_1, \dots, X_n)'$  is an iid sample with common distribution  $P_\theta$  where  $P_\theta$  form a one-parameter exponential family. If  $\{P_\theta^{(n)}\}$  is the family of distributions and  $p(x, \theta)$  are the corresponding density (frequency) functions, we have

$$p(x, \theta) = \prod_{i=1}^n h(x_i) \exp[\eta(\theta)T(x_i) - B(\theta)] = \left[ \prod_{i=1}^n h(x_i) \right] \exp[\eta(\theta) \sum_{i=1}^n T(x_i) - nB(\theta)]$$

where  $x = (x_1, \dots, x_n)'$ . Therefore, the  $\{P_\theta^{(n)}\}$  form a one-parameter exponential family.

We obtain a re-parameterization of the exponential family by letting the model to be indexed by  $\eta$  rather than  $\theta$  (Bickel and Doksum, 2000, p. 52).

The exponential family then has the form

$$q(x, \eta) = h(x) \exp[\eta T(x) - A(\eta)], x \in X \subset \mathbb{R}^p$$

where  $A(\eta) = \log \int \dots \int h(x) \exp[\eta T(x)] dx$  in the continuous case and the integral is replaced by a sum in the discrete case. If  $\theta \in \Theta$ , then  $A(\eta)$  must be finite. The model  $q(x, \eta)$  with  $\eta$  ranging over the space  $\mathcal{E}$  is called the canonical one-parameter exponential family generated by  $T$  and  $h$ . The space  $\mathcal{E}$  is called the natural parameter space and  $T$  is called the natural sufficient statistic. As in the case of  $p(x, \theta)$  for an iid sample  $X_1, \dots, X_n$  we have

$$q(x, \eta) = \left[ \prod_{i=1}^n h(x_i) \right] \exp\left[\eta \sum_{i=1}^n T(x_i) - nA(\eta)\right].$$

For example, for the Poisson distribution we have

$$p(x, \theta) = \frac{1}{x!} \exp[\log(\theta)T(x) - \theta], \quad x = 0, 1, \dots; \theta > 0,$$

with  $h(x) = 1/x!$ ,  $\eta(\theta) = \log \theta$

$$q(x, \eta)$$

where  $h(x) = 1/x!$ ,  $\eta = \log \theta$

The re-parameterized canonical

with  $\theta = (\mu, \sigma^2)'$ ,  $\mu \neq 0$ ,

$\theta = (\alpha, \beta)'$ , and the negative

of the cases the statistic  $\sum$

the mean by  $a \sum X_i$ ,  $a \in \mathbb{R}$

the normal), and  $n$ ,  $\alpha$ , and

Morris (1982) gives a character

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functions. In these cases, t

mean  $\mu$ . This latter relatio

$$\sigma^2$$

where the constants  $\zeta_0, \zeta_1,$

It can be shown that the n

variance function),  $\zeta_1 = 0$

$\zeta_1 = 1$  (linear),  $\zeta_2 = 0$ ),

$0, \zeta_2 = 1/\alpha^2$ ), the binomial

$0, \zeta_1 = 1, \zeta_2 = -1/n$ )(with

$\mu = r q/p$ ,  $g(\mu) = r q/p^2 =$

of the natural exponential

with  $h(x) = 1/x, \eta(\theta) = \log(\theta), B(\theta) = \theta, \text{ and } T(x) = x, \text{ and}$

$$q(x, \eta) = h(x) \exp[\eta T(x) - \exp(\eta)],$$

where  $h(x) = 1/x, \eta = \log(\theta), A(\theta) = \exp(\eta), \text{ and } T(x) = x.$

The re-parameterized canonical forms of the Poisson with  $\theta = \lambda,$  the normal with  $\theta = (\mu, \sigma^2), \mu \neq 0,$  the binomial with  $\theta = (n, p),$  the gamma with  $\theta = (\alpha, \beta),$  and the negative binomial with  $\theta = (r, \lambda)$  show that in each one of the cases the statistic  $\sum X_i$  is sufficient for the mean  $\mu.$  While estimating the mean by  $a \sum X_i, a \in (0, 1),$  we assume that the variance  $\sigma^2 = \sigma_0^2$  (for the normal), and  $n, \alpha,$  and  $r$  for the other distributions are fixed.

Morris (1982) gives a characterization of the normal, Poisson, gamma, binomial and negative binomial distributions. He explains that these distributions enjoy wide applications and have many useful mathematical properties because they are natural exponential families and have quadratic variance functions. In these cases, the variance is at most a quadratic function of the mean  $\mu.$  This latter relationship is given as

$$\sigma^2 = g(\mu) = \zeta_0 + \zeta_1 \mu + \zeta_2 \mu^2,$$

where the constants  $\zeta_0, \zeta_1, \zeta_2 \in \mathfrak{R}.$

It can be shown that the normal  $\mathcal{N}(\mu, \sigma^2)$  with  $g(\mu) = \sigma^2$  ( $\zeta_0 = \sigma^2$  constant variance function),  $\zeta_1 = \zeta_2 = 0,$  the Poisson,  $P(\lambda), g(\mu) = \lambda, (\zeta_0 = 0, \zeta_1 = 1$  (linear),  $\zeta_2 = 0),$  the gamma,  $\Gamma(\alpha, \beta), \mu = \alpha\beta, g(\mu) = \alpha\beta^2$  ( $\zeta_1 = 1/\alpha^2,$  the binomial,  $B(n, p), \mu = np, g(\mu) = npq = \mu - \mu^2/n, (\zeta_0 = 0, \zeta_1 = 1, \zeta_2 = -1/n)$  (with  $q = 1 - p$ ), and the negative binomial  $\mathcal{NB}(r, p), \mu = r/p, g(\mu) = r/p^2 = r(\mu + r)/r, (\zeta_0 = 0, \zeta_1 = 1, \zeta_2 = 1/r)$  are members of the natural exponential families with quadratic variance functions. Note

parameter exponential families. Suppose  $\mathbf{X} =$  distribution  $P_\theta$  where  $P_\theta$  form the family of distributions (acy) functions, we have

$$\sum_{i=1}^n T(x_i) \exp[\eta(\theta)] - nB(\theta)]$$

form a one-parameter expo-

and Doksum, 2000, p. 52).

the space  $\mathcal{E}$  is called the

called by  $T$  and  $h.$  The space

the natural sufficient

the  $X_1, \dots, X_n$  we have

$$-nA(\eta)].$$

$0, 1, \dots, \theta < 0,$

that the assumption that  $\sigma^2$ ,  $\lambda$ ,  $n$ ,  $\alpha$ , and  $r$  will remain constant while estimating the mean still holds. Based on the foregoing we now give the coefficient of variation for the respective distributions in the order they are presented above:  $v = \sigma/\mu$ ,  $\lambda^{-1/2}$ ,  $\alpha^{-1/2}$ ,  $q/(np)^{1/2}$  and  $(rq)^{-1/2}$ , respectively.

Hence, with the pertinent choice of  $v$ , the resulting improvement interval has the form

$$I(v) = \{a \in \mathfrak{R}_+ \mid \frac{1-v^2}{1+v^2} < a < 1, v \in (0, 1)\}.$$

This interval is a special case of  $I(c(n), v)$  where  $c(n) = 1$ . In fact, it is the interval of improvement given by Bibby and Toutenburg (1977).

Finally, having given the interval above we can conclude that those values of  $a$  from the open interval  $(0, 1)$  satisfying the condition in  $I(v)$  can be taken as shrinkage factors; the value  $v = 1$  gives a lower bound zero of the interval, and this bound is exactly zero. One particular case for which  $v = 1$  is the exponential distribution. Thus, for the exponential distribution, all shrunk estimators with shrinkage factors  $a \in (0, 1)$  are improvements against the unbiased estimator of the mean, namely  $\bar{X} = n^{-1} \sum_{i=1}^n X_i$ . The best among these is  $a^* = 1/(n+1)$ . The resulting improved biased estimator  $(n+1)^{-1} \sum_{i=1}^n X_i = (n\bar{X})/(n+1)$  has a smaller MSE than the variance of  $\bar{X}$ .

## Applications

In this section we provide optimal shrinkage factors for the sufficient statistic  $\sum_{i=1}^n X_i$  as an improved estimation against the unbiased estimator of the mean. Assume that  $\mathbf{X} \sim \mathcal{F}(\mu, \sigma^2)$ ,  $\mu > 0$ , where  $\mathcal{F}$  is any of the five distributions from the one-parameter exponential families we discussed above. We

use the general relationship. Then for any real valued  $a$  result in each of the cases  $t$   $a$  is the solution of the equation

### 1. The Poisson distribution

Suppose  $\mathbf{X} \sim \mathcal{P}(\lambda)$ ,  $\lambda > 0$ , and  $Var(a\bar{X}) = a^2\lambda/n$ ,  $MSE(a\bar{X}) = 2(a-1)\lambda^2 + 2a\lambda/n$  and  $(d/da)[MSE(a\bar{X})] = 0$ , we are showing that the optimal shrinkage factor is

$T = 1/(n+1)$ .

### 2. The Exponential distribution

Suppose  $\mathbf{X} \sim \mathcal{E}(\lambda)$ ,  $\lambda > 0$ , follow  $E(a\bar{X}) = a/\lambda$  and  $Var(a\bar{X}) = a^2/\lambda^2n$ ,  $(d/da)[MSE(a\bar{X})] = 2/\lambda^2 + 2/\lambda^2n > 0$ . The optimal shrinkage factor is  $a = n/(1+n)$ . Thus, the optimal estimator is

### 3. The Binomial distribution

Suppose  $\mathbf{X} \sim \mathcal{B}(n, p)$ ,  $0 < p < 1$ ,  $np$ ,  $Var(\mathbf{X}) = npq$ ;  $E(a\bar{X}) = a$ ,  $(a-1)^2n^2p^2 + a^2npq$ ,  $(d/da)[MSE(a\bar{X})] = 0$ , we are showing that the optimal shrinkage factor is

will remain constant while foregoing we now give the conditions in the order they are and  $(rq)^{-1/2}$ , respectively. If improvement interval has  $v \in (0, 1)$ .  $c(n) = 1$ . In fact, it is the Gumburg (1977). conclude that those values condition in  $I(v)$  can be a lower bound zero of a particular case for which an exponential distribution,  $\in (0, 1)$  are improvements,  $X = n^{-1} \sum_{i=1}^n X_i$ . The improved biased estimator MSE than the variance of

Suppose  $X \sim B(n, p)$ ,  $0 < p < 1$ , and  $n$  is fixed. In this case  $E(\bar{X}) = np$ ,  $Var(\bar{X}) = npq$ ;  $E(a\bar{X}) = a npq$  and  $Var(a\bar{X}) = a^2 npq$ ,  $MSE(a\bar{X}) = (a - 1)^2 n^2 p^2 + a^2 npq$ ,  $(d/da)[MSE(a\bar{X})] = 2(a - 1)n^2 p^2 + 2ampq$  and

### 3. The Binomial distribution

$$T^*(X) = \frac{1}{1+n} \sum_{i=1}^n X_i.$$

Suppose  $X \sim \mathcal{E}(\lambda)$ ,  $\lambda > 0$ , that is  $E(X) = 1/\lambda$ ,  $Var(X) = 1/\lambda^2$  from which follow  $E(a\bar{X}) = a/\lambda$  and  $Var(a\bar{X}) = a^2/\lambda^2 n$ ,  $MSE(a\bar{X}) = (a - 1)^2/\lambda^2 + a^2/\lambda^2 n$ ,  $(d/da)[MSE(a\bar{X})] = 2(a - 1)/\lambda^2 + 2a/\lambda^2 n$  and  $(d^2/da^2)[MSE(a\bar{X})] = 2/\lambda^2 + 2/\lambda^2 n > 0$ . The solution of the equation  $(d/da)[MSE(a\bar{X})] = 0$  is  $a = n/(1 + n)$ . Thus, the optimal shrunken estimator of the mean  $\lambda$  is

### 2. The Exponential distribution

$$T^*(X) = \frac{1 + n\lambda}{\lambda} \sum_{i=1}^n X_i.$$

Suppose  $X \sim P(\lambda)$ ,  $\lambda > 0$ , that is  $E(X) = \lambda = Var(X)$ . Then  $E(a\bar{X}) = a\lambda$  and  $Var(a\bar{X}) = a^2 \lambda/n$ ,  $MSE(a\bar{X}) = (a - 1)^2 \lambda^2 + a^2 \lambda/n$ ,  $(d/da)[MSE(a\bar{X})] = 2(a - 1)\lambda^2 + 2a\lambda/n$  and  $(d^2/da^2)[MSE(a\bar{X})] = 2\lambda^2 + 2\lambda/n > 0$ . Setting  $(d/da)[MSE(a\bar{X})] = 0$ , we get a solution  $a = n\lambda/(1 + n\lambda)$  for the equation, showing that the optimal shrunken estimator of the mean  $\lambda$  is

### 1. The Poisson distribution

$a$  is the solution of the equation  $d/da[MSE(a\bar{X})] = 0$ . Then for any real valued  $a$  it is  $E(a\bar{X}) = a\mu$  and  $Var(a\bar{X}) = a^2 \sigma^2/n$ . As a result in each of the cases the optimal shrinkage parameter  $a^* = a/n$ , where use the general relationship,  $E(X) = \mu$ ,  $Var(X) = \sigma^2/n$ , to derive results.

$(d^2/da^2)[MSE(a\bar{X})] = 2n^2p^2 + 2npq > 0$ . The equation  $(d/da)[MSE(a\bar{X})] = 0$  has the solution  $a = n^2p^2/(n^2p^2 + npq)$ . Thus, the optimal shrunken estimator of the mean  $np$  is

$$T^*(\mathbf{X}) = \frac{p^2}{np^2 + pq} \sum_{i=1}^n X_i.$$

#### 4. The Normal distribution

Suppose  $\mathbf{X} \sim \mathcal{N}(\mu, \sigma^2)$ ,  $\mu \neq 0$  and  $\sigma^2$  is fixed.  $E(a\bar{X}) = a\mu$  and  $Var(a\bar{X}) = a^2\sigma^2/n$ ,  $MSE(a\bar{X}) = (a-1)^2\mu^2 + a^2\sigma^2/n$ ;  $(d/da)[MSE(a\bar{X})] = 2(a-1)\mu^2 + 2a\sigma^2/n$  and  $(d^2/da^2)[MSE(a\bar{X})] = 2\mu^2 + 2\sigma^2/n > 0$ . Solving  $(d/da)[MSE(a\bar{X})] = 0$  for  $a$  gives the solution  $a = n\mu^2/(n\mu^2 + \sigma^2)$  giving the optimal shrunken estimator

$$T^*(\mathbf{X}) = \frac{\mu^2}{n\mu^2 + \sigma^2} \sum_{i=1}^n X_i$$

for  $\mu$ .

#### 5. The Gamma distribution

Suppose  $\mathbf{X} \sim \mathcal{G}(\alpha, \beta)$ ,  $\alpha, \beta > 0$ . We assume that the scale parameter  $\alpha$  is held constant. From  $E(\mathbf{X}) = \alpha\beta$ ,  $Var(\mathbf{X}) = \alpha\beta^2$  follows  $E(a\bar{X}) = a\alpha\beta$  and  $Var(a\bar{X}) = a^2\alpha\beta^2/n$ ,  $MSE(a\bar{X}) = (a-1)^2\alpha^2\beta^2 + a^2\alpha\beta^2/n$ . Hence  $(d/da)[MSE(a\bar{X})] = 2(a-1)\alpha^2\beta^2 + 2a\alpha\beta^2/n$  and  $(d^2/da^2)[MSE(a\bar{X})] = 2\alpha^2\beta^2 + 2\alpha\beta^2/n > 0$ . We get the solution  $a = n\alpha/(1+n\alpha)$  for the equation  $(d/da)[MSE(a\bar{X})] = 0$  thereby giving the shrunken estimator

$$T^*(\mathbf{X}) = \frac{\alpha}{1+n\alpha} \sum_{i=1}^n X_i$$

as the optimal estimator of the mean  $\alpha\beta$  in the sense of MSE. Observe that if  $a = 1$  we have the exponential distribution in which case the optimal shrinkage is attained at  $1/(1+n)$  as shown above.

#### 6. The Negative Binomial

Suppose  $\mathbf{X} \sim \mathcal{NB}(r, p)$ ,  $r = 1, 2, \dots$  that the parameter  $r$  (number of successes) is fixed and the probability of success  $p$  is unknown. The distribution  $E(\mathbf{X}) = rq/p$ ,  $Var(\mathbf{X}) = a^2rq/np^2$ ,  $MSE(a\bar{X}) = (a-1)^2r^2q^2/p^2 + 2arq/np^2$ , and  $(d/da)[MSE(a\bar{X})] = 2(a-1)r^2q^2/p^2 + 2arq/np^2$ , and  $(d^2/da^2)[MSE(a\bar{X})] = 2r^2q^2/p^2 > 0$ . The first derivative set equal to zero gives the solution  $a = np^2/(np^2 + rq)$ . The minimum MSE estimator is

$$T^*(\mathbf{X}) = \frac{np^2}{np^2 + rq} \sum_{i=1}^n X_i$$

It is known that the geometric distribution is a special case of the negative binomial with  $r = 1$  for which the optimal shrinkage estimator of the mean  $q/p$  is

$$T^*(\mathbf{X}) = \frac{np}{np + 1} \sum_{i=1}^n X_i$$

We note that the shrinkage factor is  $a = np/(np + 1)$ .

In conclusion we have so far considered the normal, gamma, Poisson ( $v^2 = 1/\lambda$ ), exponential ( $v^2 = \sigma^2/\mu^2$ ), and gamma ( $v^2 = \sigma^2/\mu^2$ ) distributions. In each case the shrinkage factor  $a$  approaches zero as the sample size  $n$  increases, and the optimal shrinkage factor approaches zero in which case it becomes the usual estimator. The shrinkage factor  $a_{opt}$  is useful provided it is not too small, with the exception of the case of the exponential distribution where  $a_{opt} = np/(np + 1)$ .



unknown parameters because the MSE is itself a function of the distribution parameters. And as such they are relevant from the theoretical point of view. However, whenever prior information about the size of  $v^2$  is available the shrunken estimator with minimum MSE is determined precisely. In that case the shrunken minimum MSE estimator becomes the operational substitute for the unbiased estimator  $\bar{X}$ , especially for small sample sizes, although  $\bar{X}$  is UMVUE within the class of linear unbiased estimators of the mean.

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